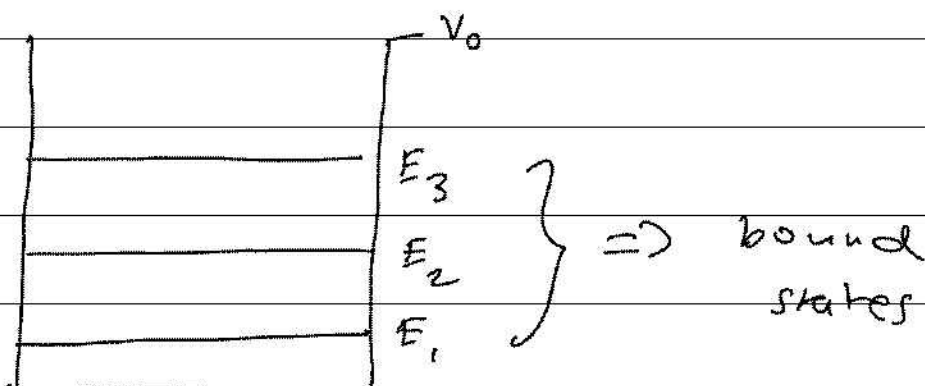


## Commutation and Uncertainty Principle



$$[\hat{A}, \hat{B}] = [\hat{A}\hat{B} - \hat{B}\hat{A}] = 0$$

$\hat{A}$  and  $\hat{B}$  commute

$$[\hat{T}_x, \hat{p}_x] = [\hat{T}_x \hat{p}_x - \hat{p}_x \hat{T}_x] f(x)$$

$$\hat{T}_x \hat{p}_x f(x) = -\frac{\hbar^2}{2m} \frac{d^2}{dx^2} \left[ -i\hbar \frac{d}{dx} f(x) \right]$$

$$= \frac{i\hbar^3}{2m} \frac{d^3 f}{dx^3}$$

$$\hat{p}_x \hat{T}_x f(x) = -i\hbar \frac{d}{dx} \left[ -\frac{\hbar^2}{2m} \frac{d^2}{dx^2} f(x) \right]$$

$$= \frac{i\hbar^3}{2m} \frac{d^3 f}{dx^3}$$

$\hat{T}_x, \hat{p}_x \Rightarrow$  ~~observables~~ operators commute

$$[\hat{x}, \hat{p}_x] \equiv [\hat{x}\hat{p}_x - \hat{p}_x\hat{x}]f(x)$$

$$\hat{x}\hat{p}_x f(x) = x \left[ -i\hbar \frac{df}{dx} \right] = -i\hbar x \frac{df}{dx}$$

$$\hat{p}_x\hat{x} f(x) = -i\hbar \frac{d}{dx} [x f(x)]$$

$$= -i\hbar f(x) - i\hbar x \frac{df}{dx}$$

$$[\hat{x}, \hat{p}_x] = i\hbar$$

$$\Delta x \Delta p_x \geq \frac{\hbar}{2}$$

Variance

$$\sigma_A^2 = \langle (A - \langle A \rangle)^2 \rangle$$

$$\langle (A - \langle A \rangle)^2 \rangle = \int \psi^* (A - \langle A \rangle)^2 \psi dx$$

$$= \int \psi^* (\hat{A}^2 - 2\hat{A}\langle A \rangle + \langle A \rangle^2) \psi dx$$

$$= \int \psi^* \hat{A}^2 \psi dx - \int \psi^* 2\hat{A}\langle A \rangle \psi dx + \int \psi^* \langle A \rangle^2 \psi dx$$

$$= \langle A^2 \rangle - 2\langle A \rangle \int \psi^* \hat{A} \psi dx + \langle A \rangle^2 \underbrace{\int \psi^* \psi dx}_{=1} - 2\langle A \rangle^2$$

$$\underline{\sigma_A^2 = \langle A^2 \rangle - \langle A \rangle^2}$$

$$\sigma_A \sigma_B \geq \frac{1}{2} \left| \int \psi^* [\hat{A}, \hat{B}] \psi dx \right|$$

$$\sigma_A \sigma_B \geq \frac{1}{2} \left| \langle [\hat{A}, \hat{B}] \rangle \right|$$

$$\sigma_A = \Delta A \quad \sigma_B = \Delta B$$

$$\sigma_x \sigma_{p_x} \geq \frac{1}{2} \left| \langle [\hat{x}, \hat{p}_x] \rangle \right|$$

$$\int \psi^* [\hat{x}\hat{p}_x - \hat{p}_x\hat{x}] \psi dx = i\hbar$$

$$\frac{1}{2} |i\hbar| = \frac{\hbar^2}{2}$$

$$\underline{\sigma_x \sigma_{p_x} \geq \frac{\hbar}{2}}$$

$$\sigma_A^2 = \langle A^2 \rangle - \langle A \rangle^2$$

$$\sigma_B^2 = \langle B^2 \rangle - \langle B \rangle^2$$

$$\underline{\sigma_A \sigma_B \geq \frac{\hbar}{2}}$$

$$\left. \begin{aligned} \sigma_A = \sigma_x &= \sqrt{\langle x^2 \rangle - \langle x \rangle^2} \\ \sigma_B = \sigma_{p_x} &= \sqrt{\langle p_x^2 \rangle - \langle p_x \rangle^2} \end{aligned} \right\} \begin{array}{l} \text{do this} \\ \text{for a particle} \\ \text{in a 1-D box} \end{array}$$

$$\sigma_x: \quad \langle x^2 \rangle = \frac{L^2}{3} - \frac{L^2}{2n^2\pi^2}$$

$$\langle x \rangle = \frac{L}{2}$$

$$\sigma_x = \sqrt{\frac{L^2}{3} - \frac{L^2}{2n^2\pi^2} - \left(\frac{L}{2}\right)^2}$$

$$\sigma_x = \frac{L}{2\pi n} \sqrt{\left[\frac{n^2\pi^2}{3} - 2\right]}$$

$$\sigma_{p_x}: \quad \langle p_x \rangle = 0$$

$$\begin{aligned} \langle p_x^2 \rangle &= 2m \langle E \rangle = 2m \cdot \frac{n^2 h^2}{8mL^2} \\ &= \frac{n^2 h^2}{4L^2} \end{aligned}$$

$$\sigma_{p_x} = \sqrt{\langle p_x^2 \rangle - \langle p_x \rangle^2} = \frac{nh}{2L}$$

$$\begin{aligned} \sigma_x \sigma_{p_x} &= \frac{nh}{2L} \cdot \frac{L}{2\pi n} \sqrt{\left(\frac{n^2\pi^2}{3} - 2\right)} \\ &= \frac{h}{4\pi} \sqrt{\left(\frac{n^2\pi^2}{3} - 2\right)} \end{aligned}$$

$$\underline{\underline{n=1}}$$

$$\sigma_r \sigma_{p_r} = \frac{\hbar}{4\pi} \sqrt{\left(\frac{\pi^2}{3} - 2\right)}$$

$$= \underline{\underline{0.58 \hbar}}$$